

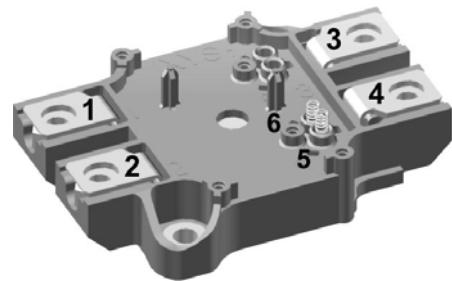
Thyristor Module

V_{RRM} = 2x 1600 V
 I_{TAV} = 200 A
 V_T = 1.13 V

Phase leg

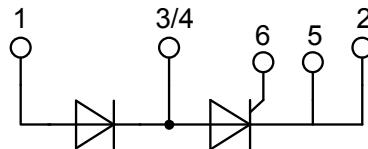
Part number

MCMA200PD1600SA



Backside: isolated

E72873



Features / Advantages:

- Thyristor for line frequency
- Planar passivated chip
- Long-term stability
- Copper base plate with Direct Copper Bonded Al2O3-ceramic
- Spring contacts for solder-free driver connection

Applications:

- Line rectifying 50/60 Hz
- Softstart AC motor control
- DC Motor control
- Power converter
- AC power control
- Lighting and temperature control

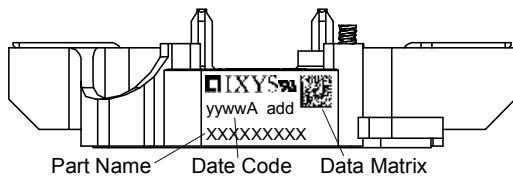
Package: SimBus A

- Isolation Voltage: 4800 V~
- Industry standard outline
- RoHS compliant
- Gate: Spring contacts for solder-free PCB-mounting
- Height: 17 mm
- Base plate: Copper internally DCB isolated
- Advanced power cycling

Rectifier

Symbol	Definition	Conditions	Ratings			
			min.	typ.	max.	
$V_{RSM/DSM}$	max. non-repetitive reverse/forward blocking voltage	$T_{VJ} = 25^\circ C$			1700	V
$V_{RRM/DRM}$	max. repetitive reverse/forward blocking voltage	$T_{VJ} = 25^\circ C$			1600	V
I_{RD}	reverse current, drain current	$V_{RD} = 1600 V$ $V_{RD} = 1600 V$	$T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		200 15	μA mA
V_T	forward voltage drop	$I_T = 200 A$ $I_T = 400 A$ $I_T = 200 A$ $I_T = 400 A$	$T_{VJ} = 25^\circ C$ $T_{VJ} = 125^\circ C$		1.16 1.40 1.13 1.44	V V
I_{TAV}	average forward current	$T_C = 90^\circ C$	$T_{VJ} = 140^\circ C$		200	A
$I_{T(RMS)}$	RMS forward current	180° sine			314	A
V_{T0} r_T	threshold voltage slope resistance	} for power loss calculation only		$T_{VJ} = 140^\circ C$	0.81 1.6	V $m\Omega$
R_{thJC}	thermal resistance junction to case				0.15	K/W
R_{thCH}	thermal resistance case to heatsink			0.08		K/W
P_{tot}	total power dissipation		$T_C = 25^\circ C$		760	W
I_{TSM}	max. forward surge current	$t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$ $t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$ $t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$ $t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$	$T_{VJ} = 45^\circ C$ $V_R = 0 V$ $T_{VJ} = 140^\circ C$ $V_R = 0 V$		6.00 6.48 5.10 5.51	kA kA
I^2t	value for fusing	$t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$ $t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$ $t = 10 \text{ ms}; (50 \text{ Hz}), \text{sine}$ $t = 8,3 \text{ ms}; (60 \text{ Hz}), \text{sine}$	$T_{VJ} = 45^\circ C$ $V_R = 0 V$ $T_{VJ} = 140^\circ C$ $V_R = 0 V$		180.0 174.7 130.1 126.3	kA^2s kA^2s kA^2s kA^2s
C_J	junction capacitance	$V_R = 400 V$ $f = 1 \text{ MHz}$	$T_{VJ} = 25^\circ C$		273	pF
P_{GM}	max. gate power dissipation	$t_p = 30 \mu s$ $t_p = 300 \mu s$	$T_C = 140^\circ C$		120 60 8	W W W
P_{GAV}	average gate power dissipation					
$(di/dt)_{cr}$	critical rate of rise of current	$T_{VJ} = 140^\circ C; f = 50 \text{ Hz}$ repetitive, $I_T = 600 A$ $t_p = 200 \mu s; di_G/dt = 0.5 A/\mu s;$ $I_G = 0.5 A; V_D = \frac{2}{3} V_{DRM}$ non-repet., $I_T = 200 A$			150	A/ μs
$(dv/dt)_{cr}$	critical rate of rise of voltage	$V_D = \frac{2}{3} V_{DRM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)	$T_{VJ} = 140^\circ C$		1000	V/ μs
V_{GT}	gate trigger voltage	$V_D = 6 V$	$T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$		2.5 2.6	V V
I_{GT}	gate trigger current	$V_D = 6 V$	$T_{VJ} = 25^\circ C$ $T_{VJ} = -40^\circ C$		150 200	mA mA
V_{GD}	gate non-trigger voltage	$V_D = \frac{2}{3} V_{DRM}$	$T_{VJ} = 140^\circ C$		0.2	V
I_{GD}	gate non-trigger current				10	mA
I_L	latching current	$t_p = 30 \mu s$ $I_G = 0.5 A; di_G/dt = 0.5 A/\mu s$	$T_{VJ} = 25^\circ C$		300	mA
I_H	holding current	$V_D = 6 V$ $R_{GK} = \infty$	$T_{VJ} = 25^\circ C$		200	mA
t_{gd}	gate controlled delay time	$V_D = \frac{1}{2} V_{DRM}$ $I_G = 0.5 A; di_G/dt = 0.5 A/\mu s$	$T_{VJ} = 25^\circ C$		2	μs
t_q	turn-off time	$V_R = 100 V; I_T = 200 A; V_D = \frac{2}{3} V_{DRM}$ $T_{VJ} = 140^\circ C$ $di/dt = 10 A/\mu s; dv/dt = 20 V/\mu s; t_p = 200 \mu s$		150		μs

Package SimBus A			Ratings			
Symbol	Definition	Conditions	min.	typ.	max.	Unit
I_{RMS}	RMS current	per terminal			300	A
T_{VJ}	virtual junction temperature		-40		140	°C
T_{op}	operation temperature		-40		125	°C
T_{stg}	storage temperature		-40		125	°C
Weight				152		g
M_D	mounting torque		3		5	Nm
M_T	terminal torque		2.5		5	Nm
$d_{Spp/App}$	creepage distance on surface / striking distance through air		terminal to terminal	14.0	10.0	mm
$d_{Spb/Abp}$			terminal to backside	14.0	10.0	mm
V_{ISOL}	isolation voltage	t = 1 second t = 1 minute	50/60 Hz, RMS; $I_{ISOL} \leq 1$ mA		4800 4000	V V

**Part number**

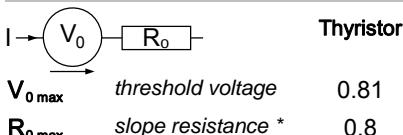
M = Module
 C = Thyristor (SCR)
 M = Thyristor
 A = (up to 1800V)
 200 = Current Rating [A]
 PD = Phase leg
 1600 = Reverse Voltage [V]
 SA = SimBus A

Ordering	Part Number	Marking on Product	Delivery Mode	Quantity	Code No.
Standard	MCMA200PD1600SA	MCMA200PD1600SA	Blister	9	510380

Similar Part	Package	Voltage class
MCMA200P1600SA	Simbus A	1600

Equivalent Circuits for Simulation

* on die level

 $T_{VJ} = 140$ °C $V_{0\max}$ threshold voltage

0.81

 $R_{0\max}$ slope resistance *

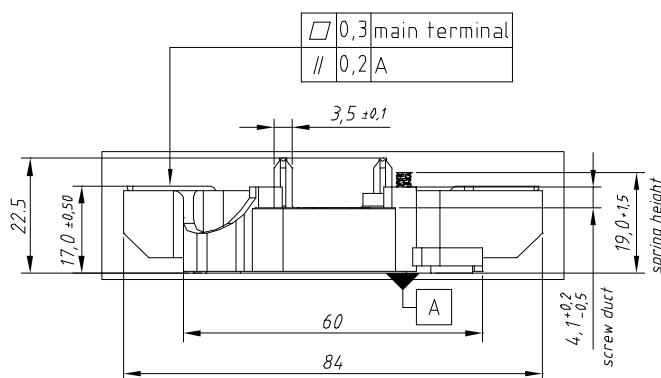
0.8

V

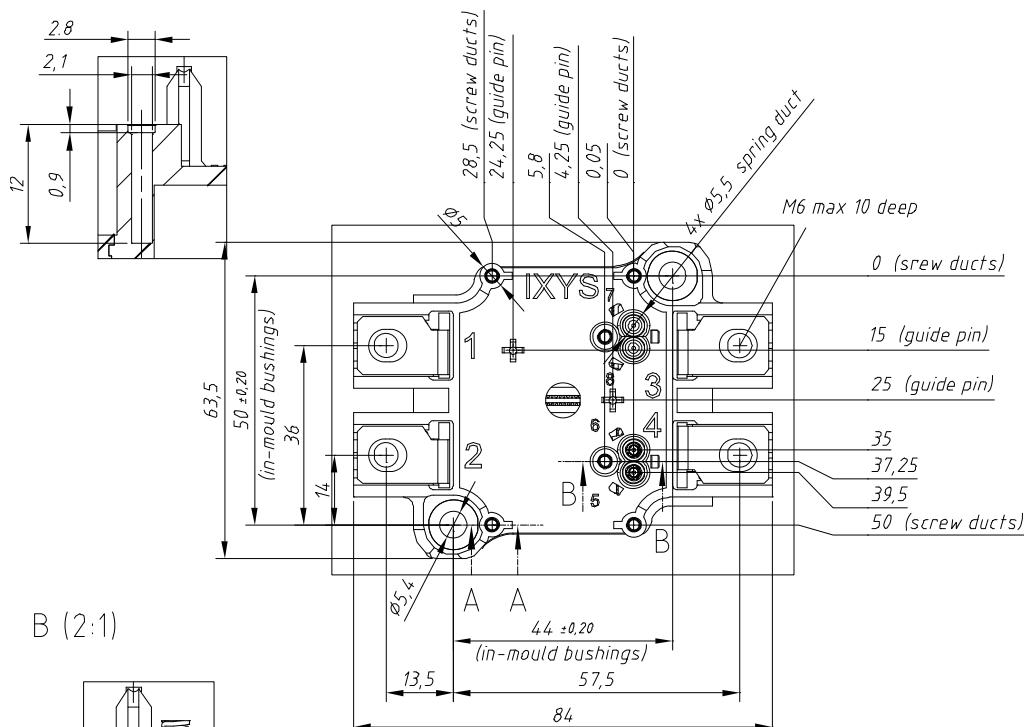
mΩ

Outlines SimBus A

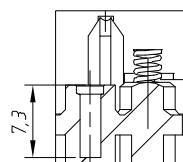
general tolerance:
ISO 2768-mK



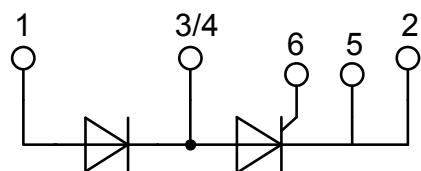
A (2:1)
screw duct (4x)



B (2:1)



Rules for the contact PCB:
 - spring landing pad = $\varnothing 3,5 \pm 0,2$; position tolerance $\pm 0,1$
 - holes guide pins = $\varnothing 4 \pm 0,1$; position tolerance $\pm 0,1$
 - holes PCB screws = $2,9 \pm 0,1$; position tolerance $\pm 0,1$



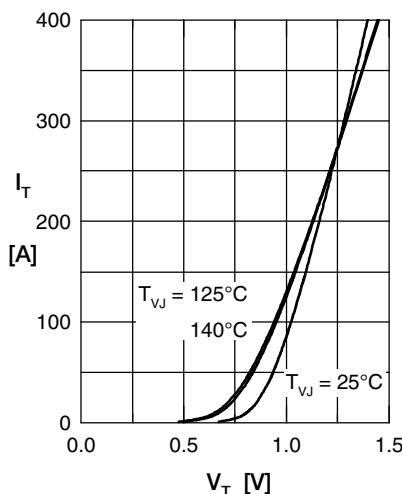
Thyristor

Fig. 1 Forward current vs.
voltage drop per thyristor

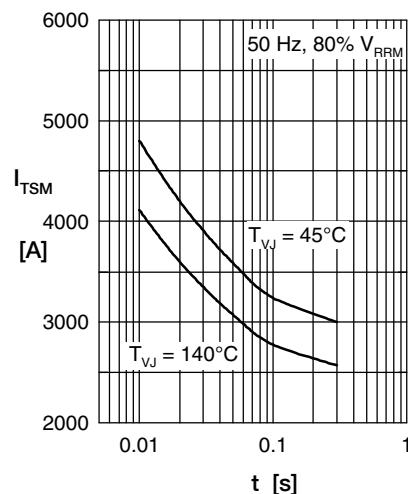


Fig. 2 Surge overload current
vs. time per thyristor

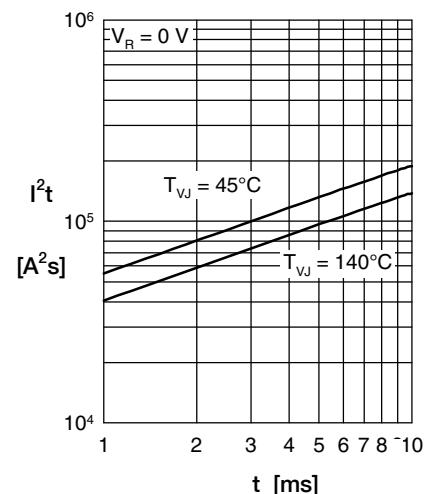


Fig. 3 I^2t vs. time per thyristor

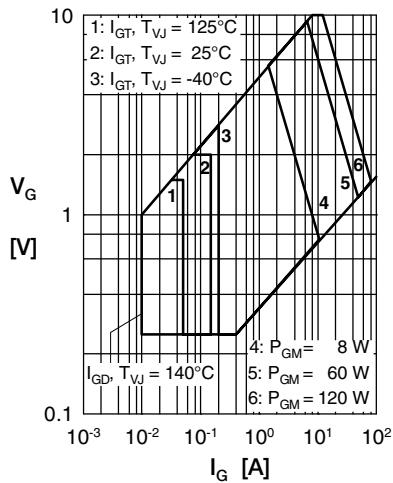


Fig. 4 Gate voltage & gate current

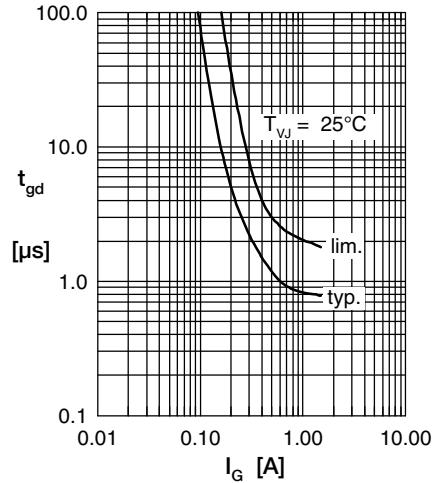


Fig. 5 Gate controlled delay time t_{gd}

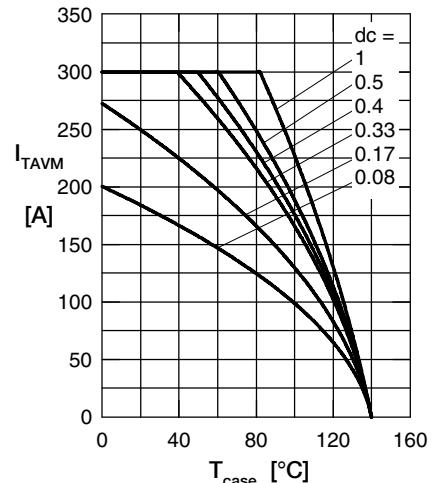


Fig. 6 Max. forward current vs.
case temperature per thy.

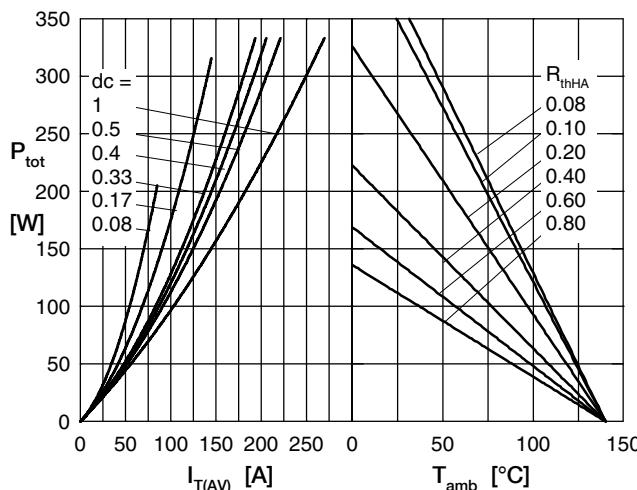


Fig. 7 Power dissipation vs. forward current
and ambient temperature per thyristor

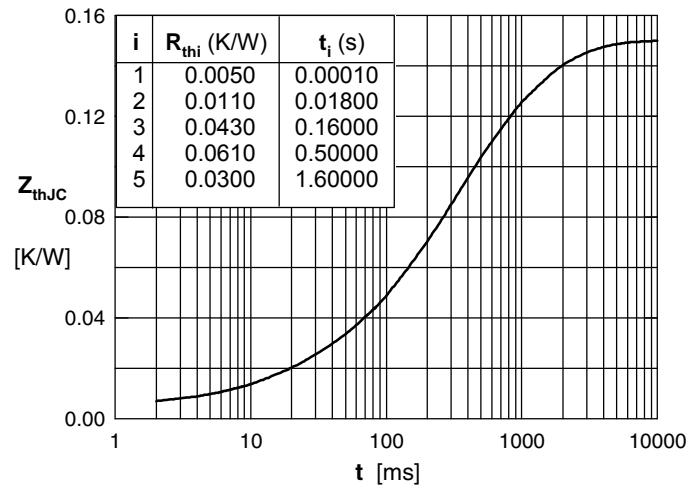


Fig. 8 Transient thermal impedance junction to case
vs. time per thyristor